Numerical Dispersion Relation for the 2D LOD-FDTD Method in Lossy Media
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Abstract—A closed-form expression is derived for the numerical dispersion relation of the 2D locally one-dimensional finite-difference time-domain (LOD-FDTD) method in lossy media. In contrast to the lossless formulation, we found that transverse-electric (TE) and transverse-magnetic (TM) waves in lossy media exhibit different numerical dispersion relations. Moreover, when the material relaxation-time constant is not well resolved by the integration time-step the TM case shows much worse accuracy than the TE case. To remove this limitation, a split-field LOD-FDTD formulation for TM waves is then considered which exhibits the same dispersion relation as the LOD-FDTD method for TE waves. The validity of the theoretical results is illustrated through numerical simulations.

Index Terms—Locally-one-dimensional finite-difference time-domain (LOD-FDTD) method, lossy media, numerical dispersion.

I. INTRODUCTION

Over the past 15 years there has been a growing interest in developing efficient unconditionally-stable finite-difference time-domain (FDTD) techniques such as the alternating-direction implicit (ADI)- and the locally one-dimensional (LOD)-FDTD methods [1]. Both ADI- and LOD-FDTD techniques were early extended to include lossy and dispersive materials [2]-[5]. As a result of the FD approximations, these methods suffer from numerical dispersion (phase errors) and numerical dissipation (amplitude errors). Both factors can be quantified by solving the numerical dispersion relation associated to the governing FD equations. This is a requisite for a mature understanding of the operation and accuracy limits of every FDTD algorithm.

The numerical properties of the ADI-FDTD method in lossy media have been extensively studied [6]-[11]. However, to the best of our knowledge, the study of LOD-FDTD formulations in lossy media has not been addressed yet.

In this letter a closed-form expression is derived for the numerical dispersion relation of the 2D LOD-FDTD method in lossy media. Transverse-electric (TE) and transverse-magnetic (TM) waves are both considered. For the sake of generality, weighted averages in time are used for discretizing the conduction terms. In contrast to what occurs in the lossless formulation, we show that TE and TM waves in lossy media exhibit different numerical dispersion relations.

For TE waves, we show that by properly selecting the values of the weighted-average parameters the accuracy of the formulation becomes independent of how well the material relaxation-time constant $\tau$ is resolved by the integration time-step $\Delta t$. On the contrary, the same is not feasible for TM waves. To remove this restriction a split-field LOD-FDTD formulation is proposed. The theoretical results are validated by actual simulations.

II. THE LOD-FDTD METHOD FOR TE WAVES

Maxwell’s curl equations for TE waves in isotropic and source-free media with permittivity $\varepsilon$, permeability $\mu$ and conductivity $\sigma$ can be expressed as

$$\frac{\partial E_x}{\partial t} = \frac{\partial H_z}{\partial y} - \sigma E_x$$
$$\frac{\partial E_y}{\partial t} = -\frac{\partial H_z}{\partial x} - \sigma E_y$$
$$\frac{\mu}{\Delta t} \frac{\partial H_z}{\partial y} = \frac{\partial E_x}{\partial y} - \frac{\partial E_y}{\partial x}$$

Following the LOD technique [12], the Crank-Nicolson scheme is first applied to (1). The resulting set of FDTD equations is then perturbed and factorized. Finally, after a further splitting into two time sub-steps, we obtain

Sub-step 1

$$E_{x}^{n+1/2} = E_{x}^{n}$$
$$E_{y}^{n+1/2} = E_{y}^{n} + \frac{\Delta t}{2\Delta x} \left( H_{z}^{n} + H_{z}^{n+1} \right)$$
$$H_{z}^{n+1/2} = H_{z}^{n} - \frac{1}{\Delta t} \left( \lambda_{y}^{(s)} E_{y}^{n} + \lambda_{y}^{(s)} E_{y}^{n+1} \right)$$

Sub-step 2

$$E_{x}^{n+1} = E_{x}^{n+1/2} + \frac{\Delta t}{2\Delta x} \left( H_{z}^{n+1/2} + H_{z}^{n+1} \right) - \frac{1}{\tau} \left( \lambda_{x}^{(s)} E_{x}^{n+1/2} + \lambda_{x}^{(s)} E_{x}^{n+1} \right)$$
$$E_{y}^{n+1} = E_{y}^{n+1/2}$$
$$H_{z}^{n+1} = H_{z}^{n+1/2} + \frac{\Delta t}{2\Delta y} \left( E_{x}^{n+1/2} + E_{x}^{n+1} \right)$$

where $\delta_{x}$ and $\delta_{y}$ are central-difference operators defined as in [8], $\tau = \varepsilon/\sigma$ and $\tau' = \tau/\Delta t$. Weighted averages have been taken for approximating the conduction terms in (2b) and (3a). We consider the weighted-average parameters subjected to the constraints $\lambda_{1}^{(s)} + \lambda_{2}^{(s)} = 1$ and $\lambda_{3}^{(s)} + \lambda_{4}^{(s)} = 1$. 
Note that the above LOD formulation involves 2 parameters \( \lambda_z^{(x)} \) per electric field component, while 4 parameters per electric field component are needed in the ADI case [8]. The reason for this is that \( E_z \) and \( E_y \) are not actually split in the LOD case. Here, for comparison purposes the parameters \( \lambda_z^{(x)} \), \( \lambda_y^{(x)} \), \( \lambda_z^{(y)} \) and \( \lambda_y^{(y)} \), used in the ADI formulation, are implicitly assumed to be zero.

Following the same approach as in [8], we find that the numerical dispersion relation in the Z-domain for (2) and (3) is

\[
-\left( \frac{Z-1}{Z+1} \right)^2 = \frac{\Delta_t^2 K_x^2}{\mu \varepsilon_y(Z)} + \frac{\Delta_t^2 K_y^2}{\mu \varepsilon_x(Z)} + \frac{\Delta_t^2 K_x^2 \Delta_t^2 K_y^2}{\mu \varepsilon_y(Z) \mu \varepsilon_x(Z)} \quad (4)
\]

with

\[
\tilde{\varepsilon}_x(Z) = \epsilon \left( 1 + \frac{1}{\pi} \frac{\lambda_z^{(x)} Z + \lambda_y^{(x)}}{Z-1} \right) \quad (5a)
\]

\[
\tilde{\varepsilon}_y(Z) = \epsilon \left( 1 + \frac{1}{\pi} \frac{\lambda_z^{(y)} Z + \lambda_y^{(y)}}{Z-1} \right) \quad (5b)
\]

and

\[
K_\xi = \frac{1}{\Delta_t} \sin \left( \frac{\tilde{\xi}_\xi \Delta_t}{2} \right) \quad (6)
\]

where \( \tilde{\xi}_\xi \) is the numerical wavenumber in the \( \xi \)-direction. Note that (4) has the same form as in the ADI case [8, eq. (12)], but with different expressions for \( \tilde{\varepsilon}_x(Z) \) and \( \tilde{\varepsilon}_y(Z) \).

By doing \( Z = \exp(j\omega \Delta_t) \) in (4), we obtain the numerical dispersion relation in the frequency domain, which reads

\[
tan^2 \left( \frac{\omega \Delta_t}{2} \right) = \frac{\Delta_t^2 K_x^2}{\mu \varepsilon_y(\omega)} + \frac{\Delta_t^2 K_y^2}{\mu \varepsilon_x(\omega)} + \frac{\Delta_t^2 K_x^2 \Delta_t^2 K_y^2}{\mu \varepsilon_y(\omega) \mu \varepsilon_x(\omega)} \quad (7)
\]

where \( \tilde{\varepsilon}_\xi(\omega) \) is the numerical complex permittivity.

A number of FD schemes with different numerical properties can be obtained depending on the specific values of the parameters \( \lambda_z^{(\xi)} \). A convenient choice is \( \lambda_z^{(1)} = \lambda_y^{(2)} = 0.5 \) and \( \lambda_z^{(2)} = \lambda_y^{(1)} = 0.5 \) which leads to

\[
\tilde{\varepsilon}_x(\omega) = \tilde{\varepsilon}_y(\omega) = \epsilon - j \frac{\epsilon}{2\tau \tan \left( \frac{\omega \Delta_t}{2} \right)}. \quad (8)
\]

As a consequence, the same dispersion relation as in the ADI case (synchronized scheme) is obtained. Moreover, with this choice, the accuracy does not depend on whether \( \Delta_t \) resolves adequately \( \tau \), as in the Crank-Nicolson method [8].

### III. The LOD-FDTD Method for TMz Waves

Maxwell’s curl equations for TMz waves can be expressed as

\[
\begin{align*}
\epsilon \frac{\partial E_z}{\partial t} &= \frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} - \sigma E_z \quad (9a) \\
\mu \frac{\partial H_x}{\partial t} &= -\frac{\partial E_z}{\partial y} \quad (9b)
\end{align*}
\]

\[
\mu \frac{\partial H_y}{\partial t} = -\frac{\partial E_x}{\partial x} \quad (9c)
\]

According to the LOD-FDTD method, (9) is discretized as follows

\[
E_z^{n+\frac{1}{2}} = E_z^n + \frac{\Delta_t \delta_x}{2\Delta_z} \left( H_y^n + H_y^{n-\frac{1}{2}} \right) - \frac{1}{\tau} \left( \lambda_1 E_z^n + \lambda_2 E_z^{n-\frac{1}{2}} \right) \quad (10a)
\]

\[
H_x^{n+\frac{1}{2}} = H_x^n \quad (10b)
\]

\[
H_y^{n+\frac{1}{2}} = H_y^n + \frac{\Delta_t \delta_x}{2\mu \Delta_x} \left( E_x^n + E_x^{n-\frac{1}{2}} \right) \quad (10c)
\]

#### Sub-step 1

\[
E_z^{n+1} = E_z^n + \frac{\Delta_t \delta_x}{2\Delta_x} \left( H_y^n + H_y^{n+\frac{1}{2}} \right) - \frac{1}{\tau} \left( \lambda_1 E_z^n + \lambda_2 E_z^{n+\frac{1}{2}} \right) \quad (11a)
\]

\[
H_x^{n+1} = H_x^n \quad (11b)
\]

\[
H_y^{n+1} = H_y^n + \frac{\Delta_t \delta_x}{2\mu \Delta_y} \left( E_x^n + E_x^{n+\frac{1}{2}} \right) \quad (11c)
\]

with \( \Sigma_{i=1}^4 \lambda_i = 1 \). Note that now the electric field is split in time but the magnetic field is not.

Following the same approach as in the TEz case, the dispersion relation in the Z-domain for (10) and (11) reads

\[
-\left( \frac{Z-1}{Z+1} \right)^2 = \frac{\Delta_t^2 K_x^2}{\mu \varepsilon_y(Z)} + \frac{\Delta_t^2 K_y^2}{\mu \varepsilon_x(Z)} + \frac{\Delta_t^2 K_x^2 \Delta_t^2 K_y^2}{\mu \varepsilon_y(Z) \mu \varepsilon_x(Z)} \frac{1}{\mu \varepsilon N(Z)} \quad (12)
\]

where

\[
N(Z) = 1 + \frac{(\lambda_2 + \lambda_4) Z + \lambda_1 + \lambda_3 \lambda_2 \lambda_4 Z - \lambda_1 \lambda_3}{\pi (Z-1)} \quad (13)
\]

and

\[
\tilde{\varepsilon}_x(Z) = \epsilon \frac{N(Z)}{1 + \frac{\lambda_2 Z - \lambda_1}{\pi (Z+1)}} \quad (14a)
\]

\[
\tilde{\varepsilon}_y(Z) = \epsilon \frac{N(Z)}{1 + \frac{\lambda_4 Z - \lambda_3}{\pi (Z+1)}} \quad (14b)
\]

By doing \( Z = \exp(j\omega \Delta_t) \) in (12), we obtain the following frequency-domain dispersion relation

\[
tan^2 \left( \frac{\omega \Delta_t}{2} \right) = \frac{\Delta_t^2 K_x^2}{\mu \varepsilon_y(\omega)} + \frac{\Delta_t^2 K_y^2}{\mu \varepsilon_x(\omega)} + \frac{\Delta_t^2 K_x^2 \Delta_t^2 K_y^2}{\mu \varepsilon_y(\omega) \mu \varepsilon_x(\omega)} \frac{1}{\mu \varepsilon N(\omega)} \quad (15)
\]

It is worth noting that (15) is exactly the same as the dispersion relation previously obtained for the ADI-FDTD method in the case of TMz waves [9, eq. (4)]. Therefore, all the discussion carried out in [9] applies to the present case and will not be repeated here. A common choice for the weighted-average parameters is \( \lambda_{1,2,3,4} = 0.25 \). However, we recall that, independently of the weighted-average parameter choice, to achieve good accuracy \( \tau \) must be well resolved by \( \Delta_t \). To overcome this limitation a split-field formulation is proposed in the next section.
IV. A SPLIT-FIELD LOD-FDTD METHOD FOR TMw WAVES

Consider the following split-field version of (9) as governing equations:

\[
\begin{align*}
\frac{\partial E_{xx}}{\partial t} &= \frac{\partial H_y}{\partial x} - \sigma E_{xx} \quad (16a) \\
\frac{\partial E_{xy}}{\partial t} &= -\frac{\partial H_x}{\partial y} - \sigma E_{xy} \quad (16b) \\
\frac{\partial H_x}{\partial t} &= -\frac{\partial}{\partial y} (E_{xx} + E_{xy}) \quad (16c) \\
\frac{\partial H_y}{\partial t} &= \frac{\partial}{\partial x} (E_{xx} + E_{xy}) \quad (16d)
\end{align*}
\]

with \( E_{xx} + E_{xy} = E_z \). Note that the above equations coincide with the Berenger split-field approach when in the latter the magnetic conductivities are set equal to zero [4], [13].

Applying the LOD-FDTD method to (16), the following set of difference equations is obtained:

**Sub-step 1**

\[
\begin{align*}
E_{xx}^{n+\frac{1}{2}} &= E_{xx}^n + \frac{\Delta t}{2 \varepsilon} \frac{\Delta x}{\Delta y} \left( H_y^n + H_y^{n+\frac{1}{2}} \right) \\
-\frac{1}{2\tau} \left( E_{xx}^n + E_{xx}^{n+\frac{1}{2}} \right) \quad (17a) \\
E_{xy}^{n+\frac{1}{2}} &= E_{xy}^n \quad (17b) \\
H_x^{n+\frac{1}{2}} &= H_x^n \quad (17c) \\
H_y^{n+\frac{1}{2}} &= \frac{\Delta t}{2 \mu} \frac{\Delta x}{\Delta y} \left( E_{xx}^n + E_{xx}^{n+\frac{1}{2}} + E_{xy}^n + E_{xy}^{n+\frac{1}{2}} \right) \\
&\quad + H_y^n \quad (17d)
\end{align*}
\]

It is worth noting that in practice (17) and (18) reduce to a one step formulation. The numerical dispersion relation and the numerical permittivity for this formulation are found to be the same as the ones given in (7) and (8), respectively. Therefore, as was discussed in section II, the condition \( \Delta t \ll \tau \) is not required to achieve high accuracy.

V. NUMERICAL RESULTS

With the aim of illustrating the validity of the above theoretical results, the numerical phase and attenuation constants in a homogeneous lossy material have been calculated. The procedure followed has been the same as the one described in [14] and previously used in [8] and [9]. All the results have been calculated at the frequency \( f = 10 \) GHz. The permittivity and permeability of the lossy material are the same as in the free space. Square cells with \( \Delta_x = \Delta_y = \Delta \) have been used for discretizing the computational domain. The spatial resolution was defined as \( N_x = \lambda_c / \Delta \), being \( \lambda_c \) the exact wavelength in the lossy material (at 10 GHz). In the same way, the temporal resolution was defined as \( N_t = T / \Delta t \), being \( T = 1 / f \) the period of the wave.

Figs. 1 and 2 display the relative errors for phase and attenuation against the propagation angle for TEw waves with parameters \( \lambda_1^{(y)} = \lambda_2^{(y)} = \lambda_3^{(y)} = \lambda_4^{(y)} = 0.5 \) and resolutions...
$N_s = 40$ and $N_t = 20$. The conductivity in Fig. 1 was $\sigma = 1.8$ S/m, consequently $\tau \simeq \Delta t$ and $\Delta t \simeq 4\Delta t_0$, where $\Delta t_0$ is the maximum stable time step allowed by the conventional FDTD method. In Fig. 2 the conductivity was $\sigma = 18$ S/m, so in this case $\tau \simeq \Delta t/10$ and $\Delta t \simeq 12\Delta t_0$. It can be seen that all the errors remain under 0.7% even though $\Delta t$ is 10 times greater than $\tau$ in Fig. 2. The theoretical results obtained by directly solving (7) have been plotted by lines and those computed by actual field simulations have been denoted by markers. Excellent agreement is observed between theory and simulation. In fact, the difference between both sets of results is typically within $10^{-5}$ %.

Fig. 3 depicts the same case as in Fig. 2 but for TM$_z$ waves with $\lambda_{1,2,3,4} = 0.25$. Now very high phase and attenuation errors can be seen for angles outside the diagonal (45°).

Finally, in Fig. 4 the same example as in Fig. 2 is considered again. The difference is that in Fig. 4 the results have been obtained by using the proposed split-field LOD-FDTD method for TM$_z$ waves. It can be seen that these results replicate those obtained in Fig. 2 for the TE$_z$ case.

VI. CONCLUSION

The numerical dispersion relation for the 2D LOD-FDTD method in lossy media has been derived in a closed-form. For TE$_z$ waves the numerical dispersion relation is, in general, different from that of the ADI case. However, if central averages are used to approximate the conduction terms the dispersion relation becomes the same as in the synchronized-scheme-ADI case [8]. A salient feature of this choice is that the condition $\Delta t \ll \tau$ is not required in order to achieve high accuracy. For TM$_z$ waves, both LOD and ADI formulations exhibit an identical numerical dispersion relation. Unfortunately, for any choice of the average parameters, the condition $\Delta t \ll \tau$ is necessary to achieve high accuracy. To overcome this limitation we have proposed a split-field TM$_z$ formulation that exhibits the same numerical dispersion relation as for TE$_z$ waves.

REFERENCES