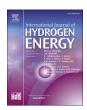
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# Hydrogen-fuelled internal combustion engines: Direct Injection versus Port-Fuel Injection

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#### ABSTRACT

The road-transport is one of the major contributors to greenhouse global gas (GHG) emissions, where hydrogen (H<sub>2</sub>) combustion engines can play a crucial role in the path towards the sector's decarbonization goal. This study focuses on comparing the performance and emissions of port-fuel injection (PFI) and direct injection (DI), in a spark ignited combustion engine when is fuelled by hydrogen and other noteworthy fuels like methane and coke oven gas (COG). Computational fluid dynamic simulations are performed at optimal spark advance and air-fuel ratio ( $\lambda$ ) for engine speeds between 2000 and 5000 rpm. Analysis reveals that brake power increases by 40% for DI, attributed to 30.6% enhanced volumetric efficiency, while the sNOx are reduced by 36% compared to PFI at optimal  $\lambda = 1.5$  for hydrogen. Additionally,  $H_2$  results in 71.8% and 67.2% reduction in fuel consumption compared to methane and COG respectively, since the  $H_2$  lower heating value per unit of mass is higher.

#### 1. Introduction

The new wave of hydrogen related studies and technological development has mainly shaken Europe due to the eagerness of achieving the goal of net zero greenhouse gases (GHGs) emissions by 2050. In this sense, transport sector represents the 25% of GHGs in the European Union (EU), and hence the European Green Deal demands a 90% emissions reduction by 2050 [1].

To address the problem of emissions related to road transport, key actors in energy transition such as public authorities and private motor companies are gradually transitioning from conventional technologies as internal combustion engines (ICEs) to electric vehicles and alternative fuels. In this sense,  $H_2$  fuelled internal combustion engines ( $H_2$ -ICEs) and fuel cell electric vehicles (FCEV) are suitable options to reduce the environmental impacts arising from conventional vehicles. Moreover,  $H_2$ -ICEs may ease the transition towards low carbon mobility in a more economical way thanks to the upgrading of current ICEs without requiring the presence of batteries and fuel cells. However, even though the use of  $H_2$  as fuel achieves zero  $CO_2$  emissions during combustion, it has associated nitrogen oxides (NOx) emissions [1,2].

Regarding the application of  $H_2$  in ICEs, the  $H_2$  molecule exhibits distinct intrinsic physicochemical properties compared with conventional fuels and other alternatives, including  $CH_4$  and coke oven gas (COG), a residual stream arising from coke production and valorised as

by-product, which consists predominantly of a  $H_2$ – $CH_4$  blend, as detailed in Table 1 [3–7].

The  $H_2$  molecule is the only one free of carbon atoms, offering a clean combustion in terms of GHG. Additionally, the lower heating value (LHV), which represents the energy released during fuel combustion per unit of mass, is nearly three times higher than conventional fuels,  $CH_4$  and COG, proving the high potential of  $H_2$  as clean energy vector. However, it has the lowest density as a consequence of the lower molecular weight, and hence, power density is penalized in gas phase, being measured per unit of volume. Finally, regarding the higher laminar flame speed ( $S_L$ ) of  $H_2$ , it helps improve the combustion efficiency, throughout the improvement in chemical reactivity [8].

Afterwards, different types of configurations which combine the ignition mechanism and injection strategies are reproduced in  $H_2$ -ICEs such as spark ignition (SI) coupled with direct or port-fuel injection (DI or PFI), and compression ignition (CI) [7].

Port-fuel injection with spark ignition (SI-PFI) is the most common strategy, which is based on injecting  $H_2$  into the intake manifold instead of directly into the combustion chamber [9–14]. In  $H_2$  SI-PFI systems the variation on the air-fuel ratio ( $\lambda$ ) exerts great influence on engine performance. The relative  $\lambda$  factor, represents the proportion of air per unit of mass of fuel in the mixture and is expressed as the coefficient of the real air-fuel ratio ( $\lambda_{real}$ ) obtained in the simulations or bench test and the stoichiometric factor ( $\lambda_{St}$ ), as defined in Eq. (1) [9].

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Nomenc	lature	$ ho_i$	Density (kg/m³)		
		$ ho_{a.i}$	Air density at atmospheric conditions (g/cm <sup>3</sup> )		
A	Area (cm <sup>2</sup> )	$\eta_e$	Volumetric efficiency (%)		
BMEP	Brake mean effective pressure (bar)	ṁ	Mass flow (g/s)		
BSFC	Brake specific fuel consumption (g/kWh)	$\dot{m_e}$	Air mass inlet flow (g/h)		
BTE	Brake thermal efficiency (%)	$m_a$	Real air mass (g)		
CAD	Crank angle degrees (°)	$\dot{m_f}$	Mass flow of fuel injected per cycle (g/s)		
CHR	Chemical heat release (J)	$m_{ m full}$	Total mass of fuel injected per cycle (g)		
dBTDC	Degrees before top dead centre (°)	λ	Relative air-fuel ratio		
dATDC	Degrees after top dead centre (°)	$\lambda_{St}$	Stoichiometric air-fuel ratio		
dBBDC	Degrees before bottom dead centre (°)	$\lambda_{real}$	Real air-fuel ratio		
dABDC	Degrees after bottom dead centre (°)	$\eta_R$	Number of crank revolutions for each power stroke per		
EOI	End of injection (°)	110	cylinder		
$H_R(T_A)$	Reagent enthalpy (J)		•		
$H_P(T_A)$	Product enthalpy (J)	Abbrevia			
HP	Horse power (HP)	CFD	Computational fluid dynamics		
LHV	Lower heating value (MJ/kg)	CI	Compression ignition		
MBT	Maximum brake torque (N·m)	COG	Coke oven gas		
N	Engine speed (rpm)	CR	Compression ratio		
PW	Pulse width (°)	DI	Direct injection		
SA	Spark advance (°)	EU	European union		
$S_L$	Laminar flame speed (m/s)	FCEV	Fuel cell electric vehicles		
sNOx	Specific nitrogen oxides (g/kWh)	GHGs	Greenhouse gases		
SOI	Start of injection (°)	H <sub>2</sub> -ICE	Hydrogen fuelled internal combustion engine		
T	Torque (N·m)	HPDI	High pressure direct injection		
TDC	Top dead centre (°)	ICE	Internal combustion engine		
$V_d$	Cylinder volume displacement (L)	PFI	Port-fuel injection		
$v_i$	Injection velocity (m/s)	rpm	Revolutions per minute		
$W_{c,i}$	Work delivered per cycle (J/cycle)	SI	Spark ignition		
WHT	Wall heat transfer (J)	SI-DI	Spark ignition – direct injection		
p	Pressure (bar)	SI-PFI	Spark ignition – port-fuel injection		
P	Power (kW)	WOT	Wide open throttle		
$P_{Inj}$	Injection Pressure (bar)				

$$\lambda = \frac{\lambda_{real}}{\lambda_{St}} \tag{1}$$

Thus, according to Verhelst et al., operating at  $\lambda$  equal to 1.4, a 50% net power output is achieved in comparison with the stoichiometric (1:1) air-fuel proportion ( $\lambda=1$ ). This enhancement is attributed to the synergistic effects of a turbocharger and an exhaust gas recirculation (EGR) system [15]. Furthermore, in the research conducted by Tang et al. a 65% of power output obtained in the same engine powered by gasoline can be obtained through a more precise optimization of the  $\lambda$  factor [16]. Despite the lower power output compared to gasoline engines, Tang et al. demonstrates that the engine brake thermal efficiency (BTE), defined as the ratio of the mechanical energy extracted from the ICE to the fuel consumed, can be enhanced to 38%, surpassing that of gasoline engines [17].

In addition, in PFI H2-ICEs fuelled by H2, the power outputs usually

range between 4.8 and 66.7 kW for engines volumes from 0.27 L (motorbikes) to 3.984 L (heavy-duty vehicles), and BTE values in the range 22.7-38% [18].

On the other side, DI configuration is based on injecting  $H_2$  directly into the combustion cylinder while the compression stroke takes place, improving the engine performance by avoiding the displacement of air. This results in a higher volumetric efficiency and thus, in higher power density than PFI systems [19].

Regarding the main differences between the PFI and the DI systems, in the latter, the injector system is positioned in the head, allowing the transport of the fuel directly to the cylinder [8]. Thus, several studies have demonstrated that high pressure direct injection (HPDI) can achieve similar efficiencies to diesel engines. Mathias et al. show that operating under ultra-lean conditions ( $\lambda=3.3$ ), BTE reaches a 35% in most tests [20]. Mohammadi et al., also achieves a maximum BTE of

**Table 1** Properties of fuels at standard conditions [3–7].

Parameter	Unit	Gasoline	Diesel	Hydrogen	Methane	Coke Oven Gas
Chemical Formula		C <sub>4</sub> –C <sub>12</sub>	C <sub>8</sub> -C <sub>25</sub>	$H_2$	CH <sub>4</sub>	COG
Composition (C, H, O, N)	Mass-%	84,16,0,0	86,14,0,0	0,100,0,0	25,75,0,0	24,46,16,14
Lower heating value (LHV)	MJ/kg	43.9	42.5	119.9	45.8	39.9
Density	kg/m <sup>3</sup>	730-780	830	0.089	0.72	0.41
Stoichiometric air/fuel ratio	kg/kg	14.7	14.5	34.4	17.2	12.72
Flammability limits	Vol-%	1.0-7.6	0.6-5.5	4.0-76.0	5.3-15.0	4.4-34.0
Laminar flame speed in air	m/s	0.37-0.43	0.37-0.43	1.85	0.38	0.68-0.88
Auto-ignition temperature	K	≈623	≈523	853	813	≈673

35% operating at lean conditions ( $\varphi = 0.5$ ;  $\lambda = 2$ ) [21]. Finally, Oikawa et al. obtained a wide range of BTE results due to the different DI approaches studied achieving a maximum of 45% [22].

Likewise, due to the shorter residence time of the fuel inside the engine, thermal efficiency values between 34 and 45.5% are obtained, using engine volumes ranging from 0.66 (motorbikes) to 7.75 L (heavyduty vehicles), even increasing power by up to 20 % compared to PFI [17,20-27].

Thus, in pursuit of enhanced engine performance, this configuration has adopted a range of injection strategies, encompassing optimized duration and timing, alongside multi-injection strategies utilizing two or more pulses per cycle [8].

Furthermore, the adoption of direct injection with spark ignition (SI-DI) techniques effectively eradicated combustion anomalies such as knock and backfiring. In these engines, direct  $H_2$  injection promotes a more homogeneous distribution of air-fuel mixture, thereby mitigating the occurrence of backfiring. This approach, coupled with  $H_2$  injection at the beginning of compression stroke, prevents knock phenomena [20, 28].

Regarding NOx, DI engines result in a 20% reduction compared to NOx levels observed in diesel engines operating at full load for maximum power output [5,8]. In addition, they exhibit a strong dependence on fuel load, showing that the results of early injection strategies increase NOx emissions, and hence, late injection is preferable at partial and low loads [8].

According to the adaptation of the ICE to be directly powered by  $\rm H_2$ , some minor modifications are required, for instance, changes in the hardware side, such as the outplacement of fuel injectors, fuel lines, charcoal filters and fuel rail and the optimization of the injection system paying special attention to the aspects of sealing and lubrication, with the aim of achieve an adequate combustion reaction [27,29–32].

Moreover, the injection strategy has a significant impact on DI performance and NOx formation. In this context, there are two main types of DI systems; low-pressure direct injection (LPDI) and high-pressure direct injection (HPDI). The type of injection has to be incorporated with a well-defined injection strategy, which in turn must be in synergy with ignition timing both in PFI and DI [8]. Thus, multiple DI strategies can be differentiated before and after the spark occurs, while in single DI is divided in late and early injections.

In  $H_2$  combustion,  $\lambda$  ratio variations exert a significant influence on combustion velocity and temperature. As reported by Luo et al.,  $\lambda$  values surpassing 1.67 yield a maximum combustion temperature below 1600 K [33]. This temperature is insufficient to furnish the activation energy required for complete combustion, leading to a degradation of engine efficiency [34]. Conversely, Eichlseder et al., maintain that combustion temperatures must be held below 1800 K to prevent the formation of harmful NOx emissions. This critical threshold is reached at  $\lambda$  lower than 1.4 [18]. Therefore, the optimum  $\lambda$  must be found ranging between 1.4 and 1.67.

Despite de existence of various works addressing the distinctions between DI and PFI engines, none quantitatively delve into the advancements and outcomes of converting petrol-fuelled ICEs to run on H<sub>2</sub>. Under this framework, the primary contributions of the present study are referred to the technological implementation and comparison of the performance between PFI-SI H<sub>2</sub>-ICEs and high performance H<sub>2</sub>-ICEs approaches, mostly based on DI-SI configurations. Moreover, other fuels such as CH<sub>4</sub> and COG have been assessed in order to validate the engine design in e-fuel applications, comparing them with H<sub>2</sub>.

This comparison was conducted through computational fluid dynamic (CFD) simulations of both engines and based on performance and emission parameters such as brake power, torque, brake mean effective pressure (BMEP), brake specific fuel consumption (BSFC), brake thermal efficiency (BTE), volumetric efficiency, chemical heat release (CHR) and specific nitrogen oxides emissions (sNOx).

#### 2. ICE design and CFD simulation

#### 2.1. Geometrical design

An experimental bench of a naturally aspirated Volkswagen Polo 1.4 L SI-PFI internal combustion engine with a compression ratio (CR) 10.5:1 was tested and computationally reproduced in a previous work reported by our research group [29]. In that work, the engine was first adapted to be fuelled by gaseous fuels. Those modifications mainly include a replacement of the plastic inlet manifold by a cast manifold and the substitution of gasoline injectors by  $\rm H_2$  injectors in stainless steel 316L, preventing gas-fuel leakages.

In the is study, the original Volkswagen engine was computationally modified to switch from PFI to DI strategy. Firstly, the new designed geometry was reproduced on Autodesk Inventor as can be seen in Fig. 1, highlighting the new shape of the intake manifold and the location of the direct injector.

The main changes in comparison with the PFI geometry model involved the removal of the gas inlet on the intake manifold, giving geometrical continuity. This modification allows better flow of gas and avoids the creation of turbulences. Subsequently, the location of the direct injector on the head of the engine is defined to avoid the interruption of the valve and piston movement paths. Furthermore, the DI system was intentionally designed to employ identical CR and displacement volume ( $V_d$ ), ensuring a comparison under consistent conditions.

The injector was designed to spray fuel through 5 nozzles positioned  $72^{\circ}$  apart and inclined  $50^{\circ}$  relative to the vertical axis of the geometry. The number and arrangement of the nozzles were optimized to enhance fuel dispersion within the cylinder, minimize injection duration, and to expand the start of injection (SOI) range. Consequently, the injector was positioned slightly off-centre from the cylinder head to accommodate the spark plug as in a real engine. In this case, the spark plug is tilted with regard to the vertical axe.

Therefore, the spark and the  $H_2$  sprayed will intersect close to the central axe of the cylinder, where chemical reaction starts. In addition, the air-fuel mixture working with early injection timing and 5-nozzle configuration is normally concentrated on the centre of the cylinder, generating a stratified and more enriched mixture for a better combustion reaction [35].

Finally, a 6.71 mm diameter was implemented based on the number of nozzles and the nozzle diameter of 0.61 mm, which was selected from well stablished studies on 5-nozzle configurations [36].

In this context, among various configurations, the 5-nozzle spray injector was selected for the superior ability of this configuration to promote a favourable mixture stratification, enhancing thermal efficiencies, without compromising NOx emissions working with  $\lambda$  close to 2, and avoiding complexities of other injection systems, which will be crucial to compare DI and PFI engine configurations [35].

The dedicated design is oriented to spark ignition and HPDI strategy, working under low loads of fuel with air-fuel ratios which ranges from 1.5 to 2 in the case of  $\rm H_2$  simulations. Thus, the low loads with early injection strategy and spark plug ignition in HPDI is the best option to obtain high brake power outputs while preventing high NOx formation, which reaches the theoretical peak at air-fuel ratios of 1.25 [8].

In this case, the early DI also offers an homogeneous mixture which helps to improve thermal efficiency and reduce NOx through a reduction in combustion temperature, even in comparison with PFI. Moreover, the general behaviour related to the existent trade-off between fuel load and NOx formation also applies to PFI systems. For this reason, early DI strategy is selected [8].

Finally, the closing and opening valve profiles in both engine configurations are the same and do not change with the variation in spark advance (SA) and start of injection (SOI) or end of injection (EOI). In this context, the main values about angles and distances are collected in Table 2.

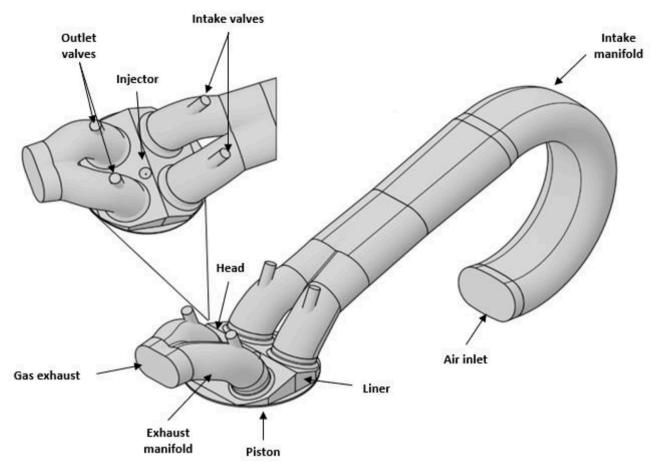


Fig. 1. Geometrical DI engine design.

Table 2
Valve profiles main values.

Intake Valves Profiles		
Opened (IVO, o)	Closed (IVC, ∘)	Max. Lift (cm)
Exhaust Valve Profiles	10.2	0.04
Opened (EVO, ∘) 19.4	Closed (EVC, ∘) 16.4	Max. Lift (cm) 0.86

Thus, the valve profiles remain unchanged across both configurations to ensure consistent operation comparable to the Volkswagen Polo 1.4L PFI. Therefore, this model has been implemented with minimal geometric changes, without altering the exhaust mixture evacuation times or air intake timings. This approach allows for a focused assessment of the resultant advantages and disadvantages derived solely from changing the injection system and the intake manifold shape. Conversely, the valve profiles are also maintained to get a suitable synergy among the different parts of the engine avoiding physical collisions between valves and piston which have been configured as moving parts.

# 2.2. CFD Simulation

The designed geometrical model is imported to ANSYS Workbench to be adapted on the computational aided design tool ANSYS SpaceClaim and meshed on ANSYS Meshing to prepare the geometry. Subsequently, simulations were carried out in the computational fluid dynamics (CFD) simulation tool ANSYS Forte.

The combustion chemistry of H2, CH4 and COG is first introduced.

Consequently, a chemical reaction pathway must be imported. In this regard, identifying a mechanism that accurately represents the combustion of each fuel is critical as all results hinge on combustion modelling. Therefore, the most comprehensive mechanism, GRI-Mech 3.0, is implemented. The GRI-Mech 3.0 effectively models  $H_2$  and  $CH_4$ , including all their possible reactions, and COG, defined as a mixture of several gases such as  $H_2$ ,  $CH_4$ , nitrogen  $(N_2)$ , carbon dioxide  $(CO_2)$  and carbon monoxide (CO) demonstrating the model completeness. Thus, this reaction model developed by the University of California, in Berkeley, comprises 325 reactions and 53 species [37].

In this sense, the GRI-Mech 3.0 optimizes the combustion reactions carried out within a temperature range among 1000 and 2500 K and airfuel ratios from 0.2 to 10. In addition, run simulations over this validation ranges could be also reasonable, as elementary reactions encompasses all the required steps deemed crucial for describing the combustion and flame propagation, including the reduction or formation of NOx [37].

The definition of the reaction mechanism is essential to establish operational parameters, a critical step in achieving optimal performance in  $H_2$ -ICE simulations. Accordingly, spark characteristics are defined to determine their crankshaft angle duration (CAD), using Eq. (2). This calculation utilizes the nominal spark angle (720°), spark time (ms), and engine speed (N) (rpm).

$$Duration = N\left(\frac{rev}{min}\right) \cdot \frac{1 \ min}{60 \ s} \cdot \frac{360 \ CAD}{1 \ rev} \cdot 1 \ ms \cdot \frac{1 \cdot 10^{-3} \ s}{1 \ ms}$$
 (2)

Furthermore, the spark advance, which characterizes the timing of spark ignition, is derived from the values previously gathered in the experimental bench and reported by our research group [18]. Therefore, two key operational parameters demand prior definition in the

simulation plan, the  $\lambda$  ratio achieved from simulations ranging from 1 to 2 and the engine speed, spanning from 2000 to 5000 rpm.

Afterwards, some other variables and parameters are defined within the simulation software, with particular emphasis on establishing appropriate boundary conditions. The boundary system encompasses inlet, outlet, and wall boundaries. Thus, beginning with the inlets, which includes the "Air Inlet", the main parameters have been compiled in Table 3 of previous experiments carried out by Ortiz-Imedio et al. [29].

In the case of the air inlet, it is important to highlight the pressure and temperature effects related to the engine speed. Regarding the pressure, the higher the engine speed, the lower the pressure used to feed the intake manifold, because when the speed increases, the piston creates a greater vacuum inside of the cylinder, reducing the pressure in the manifold. In parallel with a decrease in intake temperature upon an increase in engine speed, a corresponding drop in pressure occurs due to elevated air flow velocity. This results in lower residence time of air within the intake manifold, consequently limiting the time available for air to warm up. In this context, the outlet system consists of a single boundary condition, called the "Exhaust" condition. Thus, the "Exhaust" condition only requires an outlet pressure definition, which should be set to atmospheric pressure.

Finally, relating to the boundary conditions of the wall systems, these have a strong dependency on the wall temperature, being very closely related to the heat transfer phenomena. In this sense, Table 4 summarizes the wall boundary conditions implemented in the simulations, which were based on diverse literature sources.

As can be observed, several wall boundaries are unaffected by changes in the type of injection since they are not involved in the modified parts or in combustion reaction, and hence, they have been defined with values obtained in PFI experimental bench by our research group, keeping both systems comparable [29].

On the other hand, the walls located in the combustion cylinder region such as piston, head and liner, must be modified in comparison with PFI, in order to get a more realistic result which have been changed to the values reported in literature for DI engines [11]. Moreover, in the case of the liner, similar temperature as head is assumed.

In this sense, ANSYS Forte assumes that the heat flux through the cylinder is mainly produced as consequence of gas-phase convection, fuel-film conduction and radiation [38]. However, the temperature alongside the wall is undertake as a constant, without spatial variation, being all of them configured with the Law of the Wall slip condition for the shear stress to accurately capture wall boundary layer's effect [29, 38].

Furthermore, it is necessary to incorporate the defined profiles for the valve opening and closing movements, which are synchronized with the piston strokes, SA and SOI timings.

At this point, the main feature for modelling this type of injection on ANSYS Forte compared with PFI simulations is the Forte spray model, which allows to reproduce the injection of fuel. Afterwards, the DI 5-nozzle configuration is selected to be implemented in ANSYS Forte since it is a widely used layout and easy to reproduce. To achieve this, the dispensed jets from each injector nozzle must be modelled, being indispensable to give the exit position and the polar and cylindrical coordinates defining their trajectory, as can be seen in Fig. 2.

Additionally, simulation time is saved by assessing a single engine cylinder. This simplifies the simulation and power extrapolation for the

**Table 3**Air inlet critical boundary conditions: Pressure and Temperature [29].

Air Inlet						
Speed (rpm)	Pressure (bar)	Temperature (K)				
2000	0.92	314				
3000	0.91	311				
4000	0.89	309				
5000	0.88	307				

Table 4
Walls boundary conditions: Wall temperature (K).

Boundary Condition	Temperature (K)	References		
Piston	570	[11]		
Head	550	[11]		
Liner	550	-		
In Valve	400	[9]		
Out Valve	550	[9]		
Intake Manifold	313	[9]		
Exhaust Manifold	500	[9]		

4-cylinder engine, assuming that each cylinder is geometrically identical.

Finally, to summarize all the steps to carry out the simulation and the modelling test points, a general outline is depicted in Fig. 3.

In this sense, ANSYS Forte solves different equations such as fluid continuity, momentum and energy conservation and gas-phase mixture equation of state through different models to carry out several purposes. The explained combustion model GRI-Mech 3.0 includes all the feasible reactions with all the fuels assessed in this study, even the formation of NOx. In addition, the turbulent flow model used in this study was the Reynolds-Averaged-Navier-Stokes (RANS) Re-Normalization Group (RNG) k- $\epsilon$  model.

Finally, regarding the spray model selected, the droplet collision model is based on the adaptive collision mesh model and the solid-cone injection is initialized with the nozzle-flow model, which offers a description about nozzle discharge characteristics. This nozzle-flow model describes the instantaneous flow conditions inside the nozzle. Furthermore, unsteady gas jet model is employed in order to reduce the mesh-dependency of the Kevin-Helmholtz/Rayleigh-Taylor (KH-RT) breakup model [38].

#### 2.3. Simulation plan

Thereafter, the simulation plan requires meticulous definition of the injection velocity  $(v_i)$  and pulse width (PW), deemed as critical operational variables governing the performance and demands of each simulation. These parameters are mathematically represented in Eqs. (3) and (4) [39].

$$v_i = \frac{\dot{m}_f}{\rho_i \cdot A_{Nozzle} \cdot N_{Nozzle} \cdot 100}$$
 (3)

$$PW = \frac{N \cdot m_{full}}{\dot{m}_f} \tag{4}$$

Where  $\dot{m}_f$  is the mass fuel inlet flow (g/s),  $\rho_i$  is the density at atmospheric conditions (g/cm³),  $A_{Nozzle}$  is the cross-section of the nozzle ( $cm^2$ ),  $N_{Nozzle}$  is the number of nozzles, N is the engine speed (rpm),  $\dot{m}_f$  is the mass flow of fuel injected per cycle  $\left(\frac{g}{s}\right)$  and  $m_{full}$  is the total mass of fuel injected per cycle (g).

Finally, the simulation plan contains the values of  $\lambda$  obtained from Eq. (1) for each engine speed (rpm), the SA (dBTDC),  $v_i$  (m/s), PW (*CAD*),  $\dot{m}_f$  (g/s), the injection pressure ( $P_{lnj}$ ) and the SOI and EOI, presented in Table 5, comparing analogous experiences between DI and PFI.

In this study the simulations were executed in a workstation which uses a message passing interface (MPI) solver with two processors Intel® Xeon® Gold 6148 of 20 physical cores each one and 256 GB of RAM. Furthermore, to maximize the efficiency of the simulation workflow a Python script to post-process the ANSYS Forte results has been developed.

# 2.4. Engine performance basis

Low carbon fuel performance was compared at optimum SA and

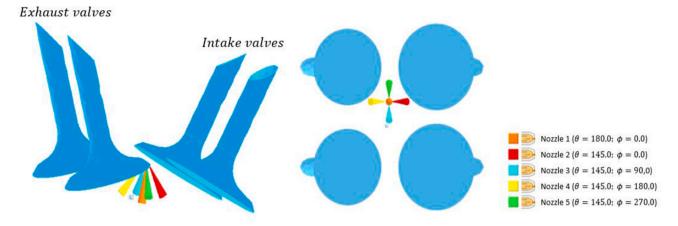


Fig. 2. Spray injection geometry at the simulation model.

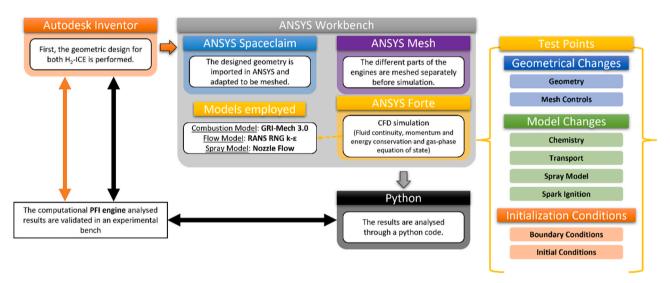


Fig. 3. General simulation procedure.

Table 5 Simulation plan.

Direct Injection (DI)											
Fuel	λ	RPM SA (di	SA (dBTDC)	DI			PFI				
				P <sub>Inj</sub> (bar); Vi (m/s)	PW (CAD)	$\dot{m}_f$ (g/s)	EOI (o)	P <sub>Inj</sub> (bar); Vi (m/s)	PW (CAD)	$\dot{m}_f$ (g/s)	SOI (°)
H <sub>2</sub>	1.5	2000	10	100; 494	15	5.83	630	3; 275	93	0.30	485
		3000	10		22	5.83	600		150	0.30	490
		4000	15		34	5.83	570		216	0.30	495
		5000	15		43	5.83	540		278	0.30	500
$H_2$	2	2000	25		12	5.83	630		76	0.30	485
-		3000	25		17	5.83	600		120	0.30	490
		4000	25		26	5.83	570		179	0.30	495
		5000	25		33	5.83	540		225	0.30	500
CH <sub>4</sub>	1.5	2000	45	100; 207	13	19.43	630	3; 115	69	1.0	485
		3000	60		20	19.43	600		107	1.0	490
		4000	60		31	19.43	570		164	1.0	495
		5000	60		39	19.43	540		201	1.0	500
COG	1.5	2000	25	100; 234	16	13.60	630	3; 150	16	0.7	485
		3000	25		25	13.60	600		25	0.7	490
		4000	25		40	13.60	570		40	0.7	495
		5000	25		49	13.60	540		49	0.7	500

wide-open throttle (WOT) conditions to reach the maximum brake torque (MBT) across all speeds and lambda ratios, using identical initial values. In this context, higher values of  $\lambda$  leads to brake power reduction,

and thus, reduced torque. This phenomenon is caused by the lower  $\rm H_2$  concentration in the air-fuel mixture.

Conversely, the higher air mass fosters an increase in volumetric

efficiency ( $\eta_e$ ), the key variable to assess the different performance of DI and PFI. This improvement in  $\eta_e$  stems from the elevated  $O_2$  proportion, as consequence of the greater air intake during the admission stroke. For this reason,  $\eta_e$  and the air mass inlet flow ( $\dot{m_e}$ ) are directly correlated, as depicted in Eq. (5) [39].

$$\eta_e = \frac{2 \cdot \dot{m_e}}{\rho_{a,i} \cdot V_d \cdot N} = \frac{m_a}{\rho_{a,i} \cdot V_d} \tag{5}$$

Where  $\rho_{a,i}$  is the air density at atmospheric conditions (g/cm<sup>3</sup>),  $m_e$  is the air mass inlet flow (g/h) and  $m_a$  is the real air mass entering into the cylinder (g).

The selected parameters to characterize the engine performance, power (P), brake mean effective pressure (BMEP) and torque are described by the following expressions presented in Eqs. (6), (7) and (8) [39].

$$P = \frac{W_{c,i} \cdot N}{\eta_R} = 2 \cdot \pi \cdot N \cdot T \cdot 10^{-3}$$
 (6)

$$BMEP = \frac{P \cdot \eta_R}{V_d \cdot N} = \frac{W_{c,i}}{V_d} \tag{7}$$

$$W_{c,i} = \oint p \cdot dV \tag{8}$$

Where  $\eta_R$  is the number of crank revolutions for each power stroke per cylinder ( $\eta_R = 2$ ),  $W_{c,i}$  is the work delivered per cycle (J/Cycle),  $V_d$  is the cylinder volume displaced by the piston in all the cylinders (dm³), p is the pressure obtained during compression stroke (bar) and N is the engine speed (rev/s).

The relationship between power and volumetric efficiency stems from power density. The displacement volume effect arises from the higher density of the air compared to H<sub>2</sub>. When H<sub>2</sub> is injected into an intake air stream, its lower density relative to air leads to occupy a greater volume in a certain physical space, displacing some of the surrounding air and hindering the entry into the combustion cylinder.

On the other hand, after adaptation to DI, the full air stream is introduced, followed by DI of  $H_2$  when inlet valve is completely closed, increasing the amount of air-fuel mixture per cm<sup>3</sup> of cylinder volume for the same  $\lambda$ , promoting the volumetric efficiency. Nevertheless,  $H_2$  is injected at higher pressure (100 bar) than the injection pressure in PFI (3 bar), requiring prior fuel energization. The high injection pressure of 100 is selected as high-speed flow injectors in DI generally requires this level of pressure to reach the instantaneous flow with  $H_2$  [30,42].

However, a primary drawback of this approach is a less stratified mixture, which could negatively impact combustion efficiency, brake-specific fuel consumption, and NOx emissions.

In this way, torque represents the rotational force generated by the engine, produced after combustion during the expansion stroke. The release of chemical heat leads to torque generation, which is subsequently converted into power. Additionally, BMEP measures engine efficiency, defined as the mean effective pressure exerted over the piston and developed during combustion. As a result, both variables are crucial to evaluate engine performance, serving as a reference of the extent to which the various forces exerted as a consequence of the combustion reaction in an ICE are utilized.

Furthermore, the engine performance, especially in  $\rm H_2$ -ICEs, apart from the widely known parameters of power, torque and BMEP, must be also assessed in terms of BTE and brake specific fuel consumption (BSFC), related to peak temperatures reached during combustion stroke and the specific nitrogen oxides emission levels (sNOx), most of them directly or inversely related with brake power and chemical heat release (CHR), as it was defined in Eqs. (9), (10) and (11) [39].

$$BTE = \frac{W_c}{m_f \cdot LHV} = \frac{\left(\frac{p_{\cdot \eta_R}}{N}\right)}{\left(\hat{m}_f \cdot \frac{\eta_R}{N}\right) \cdot LHV} = \frac{1}{BSFC \cdot LHV}$$
(9)

$$sNOx = \frac{\dot{m}_{NOx}}{P} \tag{10}$$

$$CHR = H_R(T_A) - H_P(T_A) \tag{11}$$

Where  $\dot{m}_f$  is the mass flow of fuel injected per cycle (g/s), LHV is the lower heating value in mass base (J/g),  $\dot{m}_{NOx}$  is the mass flow of generated NOx,  $H_R$  is the reagent enthalpy (J) and  $H_P$  the product enthalpy (J), both of them at ambient temperature ( $T_A$ ) (K).

Finally, regarding NOx formation, which is commonly found in  $H_2$  combustion, this process is primarily governed by temperature, according to the extended Zeldovich reaction model [40]:

$$N_2 + O \leftrightarrow NO + N$$

$$N + O_2 \leftrightarrow NO + O$$

$$N + OH \leftrightarrow NO + H$$

#### 3. Results and discussion

This section presents the major outcomes derived from the simulations that compare the performance of DI and PFI engines in terms of brake power, torque, BMEP, thermal and volumetric efficiencies, specific fuel consumption, heat release and sNOx emissions. In addition, the analysis also assesses the potential of the different low carbon fuels used in both engines, particularly focusing on H<sub>2</sub>.

## 3.1. Hydrogen engines performance comparison: DI vs PFI

#### 3.1.1. Engine performance

First, the maximum pressure reached during combustion exhibits the power delivered. In this case, the pressure curves for  $H_2$  at different engine speeds and  $\lambda$  ratios of both engines are shown in Fig. 4.

In  $H_2$  simulations, peak pressure was measured at engine speeds from 2000 rpm to 5000 rpm and  $\lambda$  ratios of 1.5 and 2. According to the results obtained, higher  $\lambda$  drives a peak pressure reduction as a consequence of lower enriched air-fuel mixtures. Conversely, peak cylinder pressure increases with engine speed (rpm). In this respect, it is important to highlight that both engines have been reproduced using the same spark advance (SA) on each simulation experience, varying in the same proportion based on  $\lambda$  factor.

Thus, in the case of PFI, working at  $\lambda=1.5$  and 5000 rpm results in a peak pressure of 65.4 bar, while DI obtains 79.4 bar. Consequently, peak pressure fuelling  $H_2$  at optimum  $\lambda~(\lambda=1.5)$  is among 8.7–21.4% higher using DI than PFI at different engine speeds.

Furthermore, this figure illustrates the disparity in SA between simulations conducted at  $\lambda=1.5$  and  $\lambda=2$  in both engines. In this context, simulations at  $\lambda=2$  exhibit an advancement of 15 crank angle degrees (CAD) compared to  $\lambda=1.5$  simulations. Consequently, when operating under leaner conditions ( $\lambda=2$ ), the combustion reaction initiates earlier, and the pressure peak is reached close to the top dead centre (TDC), resulting in a smoother slope on the curve. On the other hand, conducting simulations at the optimal air-fuel ratio ( $\lambda=1.5$ ) portrays a steeper slope, from 710 CAD at 2000–3000 rpm and 705 CAD at 4000–5000 rpm. This abrupt increase means that the combustion reaction occurs in less time than under leaner conditions as consequence of the higher flame temperature generated, which promotes the laminar flame speed ( $S_L$ ), leading to higher pressure peaks. Therefore, a more efficient combustion reaction with a faster release of energy and higher combustion temperatures is achieved.

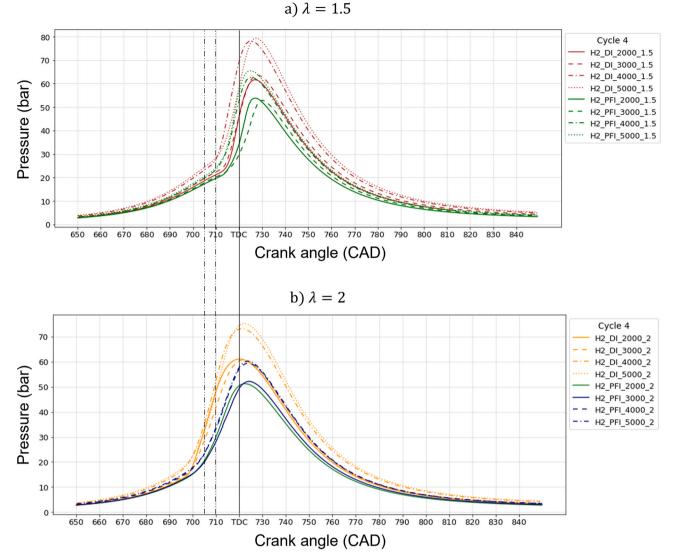


Fig. 4.  $H_2$  -ICE pressure analysis during combustion at different air-fuel ratios a)  $\lambda=1.5$  and b)  $\lambda=2$ .

It is worth noting that there is a direct relationship between pressure and power which also affects to torque and BMEP by means of  $W_{c,i}$ . The higher peak pressure in DI is enabled by the enhancement in volumetric efficiency as consequence of a better distributed and homogeneous mixture inside the cylinder, which increases the power density. However, the increase in pressure leads to a simultaneous increase in temperature, promoting the formation of thermal NOx.

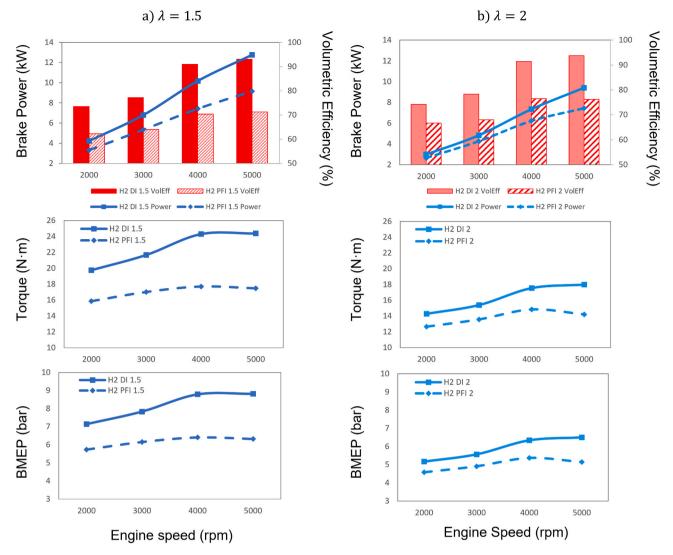
In this context, Fig. 5 presents the key engine performance metrics, encompassing brake power depicted as lines, volumetric efficiency represented as columns, torque and BMEP, which are influenced by engine speed (rpm) and  $\lambda$  ratio.

In this case, simulations conducted at optimal air-fuel ratio (Fig. 5a,  $\lambda=1.5$ ) reveal a notable discrepancy in volumetric efficiency between PFI and DI, ranging from 18.3% to 30.6% higher in the case of DI. This difference persists across the entire engine speed range, correlating with a corresponding power increase between 27.3% and 39.5%. The observed difference among type of engines arises as a result of the displacement volume effect. In PFI configuration, the process impedes air intake due to the lower density of  $\rm H_2$ , requiring a larger volume per mass unit. Consequently, a reduced quantity of air-fuel mixture is introduced to attain the desired  $\lambda$  ratio, and hence, control over the dosage is more complex. This leads to a decline in power density and simultaneously a decrease in the released energy while combustion is

taking place.

Accordingly, an increase in engine speed conducts to greater intake and expulsion of the air-fuel mixture, resulting in combustion reactions that generate more thermal energy in each cycle. As a result, higher engine speeds yield more power. Furthermore, this leads to an enhanced volumetric efficiency using DI configuration, which ranges from 73.6% to 93.1% and a brake power that ranges from 4.2 kW to 12.8 kW within that engine speed range for just one cylinder analysed. Consequently, considering the 4-cylinder engine configuration, an approximately 11 kW more powerful engine is obtained adapting the configuration from PFI to DI, assuming a total increase of 14.8 horse power (HP).

Conversely, simulations performed under leaner conditions (Fig. 5b,  $\lambda=2$ ), yield lower performance as less air is introduced per cycle, thereby reducing the available energy during combustion. However, in case of DI, compared to optimal air-fuel ratio (Fig. 5a,  $\lambda=1.5$ ), volumetric efficiency remains unaffected since the amount of air introduced keeps constant while fuel mass is reduced. On the other hand, in PFI configuration, under leaner conditions, as consequence of the lower amount of fuel injected, a higher amount of air is introduced inside of the cylinder enhancing volumetric efficiency, although the lower fuel concentration in mixture causes a power output detriment. Consequently, brake power decreases when operating at  $\lambda=2$  compared to  $\lambda=1.5$ . Specifically, DI delivers among 35.6%–41.4% less power from



**Fig. 5.** H<sub>2</sub> engine performance comparison at different air-fuel ratios a)  $\lambda=1.5$  and b)  $\lambda=2$ .

2000 to 5000 rpm, while the PFI engine experiences a reduction from 19.3% to 25.4%.

Thus, DI configuration achieves closer results, in terms of brake power, to the PFI configuration operating at  $\lambda=2$ , although there is still a gap between them ranging from 12.8% to 26.5% in favour of DI.

Finally, torque and BMEP are plotted against various engine speeds and air-fuel ratios, operating at  $\lambda=1.5$  (Fig. 5a) and  $\lambda=2$  (Fig. 5b). Under optimal conditions (Fig. 5a,  $\lambda=1.5$ ), a comparable pattern is noted in both variables, mirroring the trends observed in the brake power results because both are directly related, with torque and BMEP in DI being 27.3%–39.5% greater than PFI. In contrast, under lean conditions (Fig. 5b,  $\lambda=2$ ), torque and BMEP experienced reductions ranging from 34.9% to 40.7% compared to optimal  $\lambda$ . However, DI configuration results still exhibit a superiority of 12.8%–26.5% over PFI.

# 3.1.2. Thermal efficiency and emissions

Once engine performance parameters are assessed, as consequence of the higher performance achieved at the optimal air-fuel ratio ( $\lambda=1.5$ ), this value is predetermined for analysing thermal efficiency and emissions behaviours in both engine configurations.

As illustrated in Fig. 6, the selected variables for describing thermal efficiencies are the chemical heat release (CHR), brake thermal efficiency (BTE) and brake specific fuel consumption (BSFC), which is represented by the blue line. Fig. 6 also depicts, sNOx and maximum

combustion temperature reached across the entire range of engine speeds.

In this context, the elevation in engine speed involves an increased chemical heat release (CHR) per cycle due to the growth in the air-fuel mixture introduced. Moreover, brake specific fuel consumption (BSFC) rises despite the power gain as consequence of the higher injection flowrate  $(m_f)$ . Therefore, as engine power increases, BTE diminishes as a result of the indirect correlation with BSFC.

In the obtained results, simulation runs at the optimal air-fuel ratio ( $\lambda=1.5$ ),  $H_2$  attains elevated CHR levels using a DI engine in comparison with PFI configuration. This is attributed to the enhanced capacity of DI to introduce a greater quantity of air-fuel mixture, culminating in higher CHR values, effectively transforming more chemical energy into mechanical energy. Consequently, the utilization of DI instead of PFI leads to percentage increase in CHR ranging from 19.0% to 35.5%, which results in an additional CHR amount of 883.3 J/cycle when considering the entire 4-cylinder engine.

The rise in brake power requires a widening pulse width (PW) as a consequence of the corresponding increase in the amount of fuel mass injected. Thus, BSFC values elevate as engine speed increases. Nevertheless, the lower power output of PFI engines negatively impacts BSFC, despite their lower fuel consumption per cycle compared to DI engines. In this context, DI results in a percentual reduction of BSFC compared to PFI, ranging from 1.4% to 4.8%.

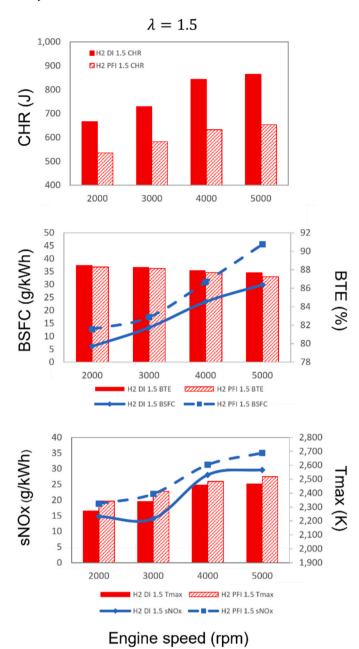


Fig. 6. Heat released, thermal efficiency and NOx emission comparison in  $\rm H_2$  engines.

Conversely, BTE and BSFC display strong interdependency, with brake power significantly influencing them. In this sense, BTE diminishes with the increase in BSFC, stemming from the heightened fuel requirement to generate an equivalent amount of energy, resulting in greater losses. Subsequently, upon analysing the entire range of engine speeds (rpm), the utilization of DI configuration contributes to the increment of BTE between 0.5% and 1.7% compared to PFI. Specifically, H<sub>2</sub> attains a peak BTE of 37.6% and a minimum BSFC of 79.7 g/kWh.

Finally, NOx emissions exhibit a direct proportional relationship with combustion temperature, which increase with the engine speed as consequence of the greater amount of heat released during combustion.

In the DI system, air is introduced before hydrogen injection, reducing the tendency to pre-ignition and also lowering the local incylinder temperature, as consequence of  $H_2$  expansion derived from high-pressure direct injection [27]. This leads to the formation of a more homogeneous air-fuel mixture, fostering more efficient and uniform

combustion, converting more energy released into useful work instead of remanent heat [41].

Moreover, the reduction of WHT losses leads to better mixing, and hence, the local peak temperatures in the cylinder are reduced [43]. Therefore, an increase in CHR using the DI configuration compared to PFI suggests an increase in useful power, but not a temperature increase, as WHT losses are reduced.

Thus, the maximum temperature reached in DI is reduced between 25.5K and 73.9K, together with a decrease in sNOx ranging from 10.4% to 36.0% compared to PFI. In addition, DI system reaches the minimum levels of sNOx at 3000 rpm (14.06 g/kWh), as consequence of the higher brake power augmentation in comparison with 2000 rpm.

In the PFI configuration, the air excess burns a larger quantity of  $\rm H_{2}$ , which possesses a higher LHV, further elevating the mixture temperature at high engine speeds and subsequently promoting the formation of thermal NOx. For instance, a peak temperature rise of 266.1 K is observed from 3000 rpm to 4000 rpm.

Consequently, it can be concluded that the  $\rm H_2\text{-}ICE$  DI exhibits superior power output and lower emission levels compared to PFI, under the studied conditions.

#### 3.2. Low carbon fuels performance comparison: DI vs PFI

#### 3.2.1. Engine performance

Ansys® Forte® software enables the assessment of different fuel types, using the same variables and parameters. This facilitates the comprehensive analysis of the performance, including previous  $\rm H_2$  results, and those obtained in CH<sub>4</sub> and COG simulations at ( $\lambda=1.5$ ). Fig. 7 depicts the comparison of the performance of the three fuels at the H<sub>2</sub> optimal air-fuel ratio ( $\lambda=1.5$ ) within the entire range of engine speeds (2000–5000 rpm). Thus, brake power, volumetric efficiency, torque and BMEP are assessed for both injection systems.

In PFI configuration (Fig. 7a), the maximum power output achieved is 9.5 kW when utilizing COG at 5000 rpm. The superior brake power observed in COG is attributed to the higher  $S_L$  compared to CH<sub>4</sub>, leading to higher efficiencies since a more complete combustion is achieved. Conversely, COG has a greater density than H<sub>2</sub> and a substantial amount of energy is delivered during combustion owing to higher volumetric efficiency. In this sense, compared to H<sub>2</sub>, brake power increases from 0.9% (+0.1 kW/cyl) to 12.7% (+0.6 kW/cyl), and compared to CH<sub>4</sub> brake power spans from 10.0% (+0.3 kW/cyl) to 30.2% (2.86 kW/cyl) in favour of COG within the entire range of engine speeds.

In addition, the obtained volumetric efficiency is among 7.5%–10.8% greater running COG in PFI engines than  $H_2$ . The enhanced volumetric efficiency stems from the higher volumetric density of COG, which is in mass % primarily composed by CH<sub>4</sub>. This increased density mitigates the effect of volume displacement at the inlet, leading to gains in volumetric efficiency. Furthermore, COG volumetric efficiency remains lower than CH<sub>4</sub> ranging from 4.7% to 6.7%. The volumetric efficiency of COG reaches the maximum at 4000 rpm, resulting in the highest power difference between fuels. Therefore, PFI system finds a performance limitation on 4000 rpm, reaching almost the same peak pressure as seen in the latter simulation at 5000 rpm while injecting more amount of fuel and reducing the overall efficiency. This limitation is overcome by changing the injection system to DI, which means that DI engine could even work at higher speeds resulting in a performance improvement.

Regarding DI configuration (Fig. 7b),  $H_2$  achieves a maximum power output of 12.8 kW at 5000 rpm. Moreover,  $H_2$  obtains the highest brake power using the DI configuration, even generating a power output 21.9% higher than COG and 78.9% higher than CH<sub>4</sub> both fuelled in DI engines. Thus, CH<sub>4</sub> is greatly disadvantaged while working over the  $\lambda_{SI}$ , where CH<sub>4</sub> optimal combustion conditions are normally achieved.

This power enhancement in  $H_2$  combustion simulations is obtained as consequence of the growth of volumetric efficiency. In this context,  $H_2$  exhibits the greatest sensitivity to engine changes in volumetric

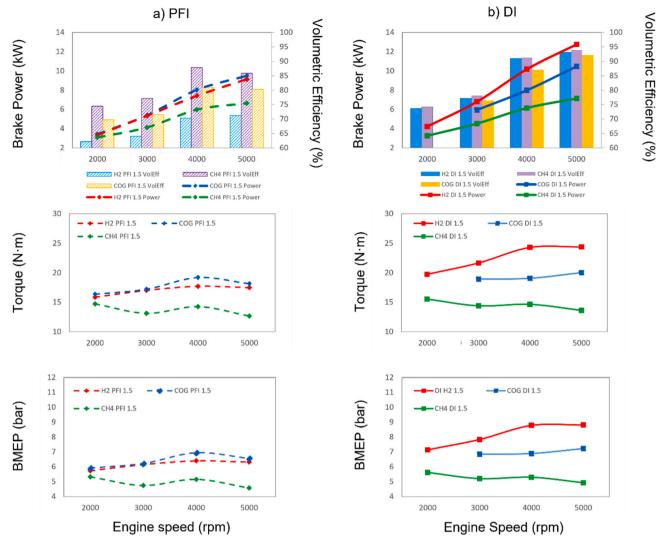


Fig. 7. Low carbon fuels engine performances comparison with different engine configurations a) PFI and b) DI.

efficiency among the analysed fuels. However, in every case the volumetric efficiency is improved, and hence, the brake power. In accordance,  $\rm H_2$  increases volumetric efficiency by 30.6% in the maximum, COG by 14.8% and CH<sub>4</sub> by 9.4%, since  $\rm H_2$  has the lowest density and CH<sub>4</sub> the highest one.

Finally, torque and BMEP follows the same trends as brake power and volumetric efficiency. Accordingly, the maximum torque in the PFI configuration is achieved when employing COG as fuel and operating at 4000 rpm due to the higher brake power reached at this engine speed, generating 19.2 N m and achieving a maximum BMEP of 6.9 bar. In contrast, the DI configuration reaches the maximum torque and BMEP using  $\rm H_2$  at 5000 rpm, resulting in 24.4 N m and 8.82 bar. This means a noteworthy enhancement in conversion efficiency of heat released into useful work, as evidenced by the increase in BMEP values. This improvement indicates a more favourable response in a high-load due to the increased torque, in addition to the greater brake power delivered.

Thus,  $\rm H_2$  is the best fuel compared at the designed DI engine in terms of engine performance with regard to the final results and improvement. Conversely, it is important to highlight that COG is obtained after valorisation of an industrial residual gas stream, although it has intermediate properties between  $\rm H_2$  and  $\rm CH_4$  regarding density, LHV, and  $\rm S_L$ .

#### 3.2.2. Emissions and thermal efficiency

As illustrated in Fig. 8, the performance and the efficiency are assessed together with the emissions associated with each fuel used in DI

and PFI configurations. CHR, wall heat transfer (WHT) and maximum combustion temperature are represented by bars, and, sNOx are represented by trend lines. Finally, the comparison between BTE and BSFC is also illustrated.

Regarding the PFI configuration (Fig. 8a), it is observed that the assessed fuels deliver comparable CHR. However, within this configuration, COG achieves the lowest wall heat transfer (WHT) values at optimal air-fuel ratio ( $\lambda=1.5$ ). Consequently, H<sub>2</sub> experiences higher wall losses than COG, from 2.9 to 20.3 J/cycle, while CH<sub>4</sub> incurs losses 23.6–70.6 J/cycle above COG levels. This discrepancy in WHT contributes to COG and H<sub>2</sub> showing significantly higher brake power than CH<sub>4</sub>, because more heat is converted into useful work, even though CHR is similar and lower combustion temperatures are achieved. In the case of CH<sub>4</sub>, this effect occurs due to the negative work generated as consequence of reaching the pressure peak before the TDC, while piston keeps compressing and reducing the effective work.

In light of the above, the elevated combustion temperatures during  $CH_4$  combustion, foster the formation of thermal NOx, resulting in the highest observed sNOx levels. In contrast, the mitigating effect of  $CH_4$  when mixed with  $H_2$  leads to a reduction in sNOx emissions during COG combustion, showcasing reductions ranging from 31.9% to 111.6% compared to  $H_2$ . In this sense,  $CH_4$  results in higher combustion temperatures but also in greater WHT, as consequence of the lower BTE.

Regarding efficiency, within the PFI configuration, H<sub>2</sub> is emerging as the fuel with the minimum energy consumption for power generation,

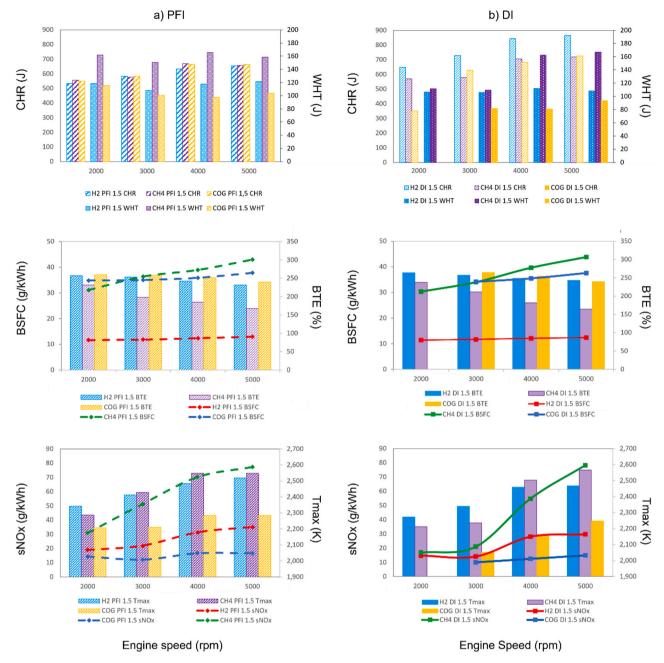


Fig. 8. Performance, efficiency and sNOx emissions comparison in low carbon fuels with different engine configurations a) PFI and b) DI.

also manifests a high thermal efficiency similar to the COG. Furthermore, relating to BSFC,  $\rm H_2$  exhibits values between 65.5%-66.5% and 62.5%-69.9% lower values than COG and CH<sub>4</sub>, respectively.

In DI simulations (Fig. 8b) working under identical conditions ( $\lambda=1.5$ ), since  $H_2$  obtains the highest power output, it also releases the greatest amount of chemical heat, exceeding the CHR obtained for the COG at the same  $\lambda$  between 16.4% and 28.8% and showing the higher chemical combustion potential of  $H_2$  compared to other fuels.

Moreover, when simulating within this injection system, COG presents intermediate results between  $\rm H_2$  and also  $\rm CH_4$  for DI. This results in an improvement of CHR by 9.4% at maximum engine speed after enhancing the volumetric efficiency of the air-fuel mixture through the transition from PFI to DI configuration.

However, the combustion of  $H_2$  results in greater energy losses through the walls, that exceed of those of COG by 4.2–25.7 J/cycle, and  $CH_4$  also experiences losses from 8.7 to 65.3 J/cycle above COG. In

addition, when compared to PFI, the WHT for  $\rm H_2$  is reduced from 2.0% to 10.9%, COG spans from 10.2% to 19.1% and for  $\rm CH_4$  from 0.9% to 28.7%. This reduction in thermal losses is attributed to the improved combustion reaction facilitated by DI strategies, mitigating the effect of incomplete reaction zones that release inefficient heat.

In the case of sNOx, emission levels increase considerably at high speeds, reaching in CH $_4$  simulations a value of 78.3 g/kWh that is almost twice the sNOx emissions of DI H $_2$  at 5000 rpm.

In the case of  $\rm H_2$  simulations, the maximum emissions value is 29.6 g/kWh, representing a reduction of 62.1% in sNOx compared to CH<sub>4</sub>. However, this value is 55.7% higher than the emissions generated using COG. Consequently, the inclusion of a mixture of CH<sub>4</sub> and H<sub>2</sub>, represented in COG simulations exhibits NOx-reducing properties, achieving the lowest sNOx levels of the three, even at maximum engine speed, measuring 14.9 g/kWh at 5000 rpm. Additionally, COG reduces the maximum combustion temperature in the range of 219.0 K–305.0 K

compared to H<sub>2</sub>.

Therefore, DI systems contributes to reduce sNOx emission levels in all scenarios. In summary, DI reduces sNOx emissions 7.9 g/kWh for  $\rm H_2$  at 3000 rpm, 4.2 g/kWh for COG at 4000 rpm and 30.3 g/kWh for CH<sub>4</sub> at 3000 rpm, compared to PFI.

Finally, regarding BTE and BSFC,  $H_2$  achieves the best values, similar in DI and PFI configurations. However,  $H_2$  reduces BSFC in the range of 62.4%–71.8% compared to  $CH_4$  and 65.8%–67.2% compared to CG. In terms of BTE, both  $H_2$  and CG achieve comparable results. However,  $H_2$  consistently outperforms  $CH_4$  by a margin of 3.7%–11.3%. This superiority stems from the exceptional calorific power per unit mass of  $H_2$  and remarkable thermal efficiencies, which facilitate a more efficient energy potential conversion. Therefore, despite the need for high compression of  $H_2$  to achieve autonomy,  $H_2$  remains the preferred choice of fuel, specially achieved in DI engines.

#### 4. Conclusions

In this work a comparative simulation study of the engine performance in DI and PFI has been carried out, both adapted to be fuelled by different low carbon fuels  $H_2$ ,  $CH_4$  and COG. The simulation model has been developed based on a naturally aspirated Volkswagen Polo 1.4 L SI engine. Thus, simulations were focused on two main parameters with influence on engine performance, air-fuel ratio ( $\lambda = 1$ -2) and engine speed (2000–5000 rpm).

Regarding H<sub>2</sub> simulations, the main conclusions drawn are.

- A CFD model was developed for DI  $H_2$ -ICE, showing a performance improvement. Simulations reveal that working under optimal airfuel ratio conditions ( $\lambda=1.5$ ), the DI  $H_2$ -ICE model increases a brake power by 39.5% and the volumetric efficiency by 30.6% compared to the PFI system. These findings corroborate the detrimental effect of volume displacement on engine performance, a characteristic limitation of PFI gas fuel combustion systems. On the other hand, torque and BMEP increases in the same proportion.
- Concerning sNOx emissions, the DI offers a prominent NOxreduction potential, emitting a maximum of 29.6 g/kWh, which suppose a 36% reduction compared to PFI. This reduction is achieved through the lower value of the maximum temperature reached and the higher power delivered which is inversely proportional to sNOx.
- Using DI configuration,  $\rm H_2$  attains a peak BTE of 37.6% and a minimum BSFC of 79.7 g/kWh, performing better than PFI. In addition, the utilization of DI instead of PFI leads to a 35.5% more energy released, which results in an additional CHR amount of 883.3 J/cycle when considering the entire 4-cylinder engine.
- Leaner  $H_2$  mixtures ( $\lambda=2$ ) experience lower combustion pressures and temperatures, leading to reduced performance. Specifically, DI delivers among 35.6%–41.4% less power.

On the other hand, comparing the performances obtained by different fuels.

- $H_2$ -DI simulations running at the optimum air-fuel ratio ( $\lambda=1.5$ ) show the best engine performance, generating a power output 21.9% and 78.9% higher than COG and CH<sub>4</sub> respectively. In these cases, simulations present the same differences in torque and BMEP.
- COG exhibits the lower sNOx levels since the mixture  $H_2$ –CH<sub>4</sub> greatly reduces NOx while keeping good performances. However,  $H_2$ -DI configuration still reduces the sNOx levels by 62.1% compared to pure CH<sub>4</sub> at  $\lambda=1.5$ .
- Regarding BSFC, the  $H_2$ -DI combination at  $\lambda=1.5$  achieves the most favourable performance. Thus,  $H_2$  is the more efficient option resulting in a reduction of 71.8% in BSFC compared to CH<sub>4</sub> and 67.2% compared to COG at the same operating conditions, due to the higher LHV per mass unit.

 BTE is very similar in COG and H<sub>2</sub> simulations in both injection systems, while CH<sub>4</sub> achieves the lowest values, losing big amounts of thermal energy during combustion in excess of air.

These findings underscore the necessity of further research on DI  $\rm H_2$ -ICEs, considering the evident improvements in engine performance and the high levels of efficiency achieved. DI  $\rm H_2$ -ICEs demonstrate competitiveness not only with dedicated  $\rm H_2$  engines but also with other low carbon fuels and even gasoline engines in terms of power output and emissions generation. Moreover, DI technology offers ease of implementation compared to other technologies and the ability to employ synthetic fuels or even fuels recovered from waste streams such as COG. These advantages position DI engines as frontrunner in the decarbonization of road transport.

#### CRediT authorship contribution statement

Fabián Musy: Data curation, Formal analysis, Investigation, Methodology, Software, Writing – original draft. Rafael Ortiz: Conceptualization, Investigation, Methodology, Software, Supervision. Inmaculada Ortiz: Funding acquisition, Investigation, Supervision. Alfredo Ortiz: Conceptualization, Data curation, Formal analysis, Funding acquisition, Investigation, Methodology, Supervision, Writing – original draft, Writing – review & editing.

### Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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